The application of Schur's algorithm to an inverse eigenvalue problem

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Abstract. Anderson recently developed an algorithm for the inverse eigenvalue problem for the Sturm-Liouville equation in impedance form. The impedance A(x) is assumed to be piecewise constant over N equal intervals. In this paper we show that Andersson's algorithm is equivalent to Schur's algorithm, which is well known in one-dimensional seismology and transmission line theory, and is known to be numerically efficient and stable.

1. Introduction

In a recent paper, Andersson [1] considered the inverse eigenvalue problem for the Sturm-Liouville equation in impedance form, namely

$$(A(x)w'(x))' + \omega^2 A(x)w(x) = 0 \qquad 0 \leqslant x \leqslant L$$
(1.1)

subject to the end conditions

I.
$$w'(0) = 0 = w'(L)$$

II.
$$w(0) = 0 = w'(L)$$
.

Equation (1.1) describes the infinitesimal, free, longitudinal vibrations of a thin, straight rod of cross-sectional area A(x) under 'free-free' (I) or 'fixed-free' (II) end conditions; ω is the (scaled) natural frequency. He showed that if there were given eigenvalues $(\omega_k)_0^N$ such that

$$0 = \omega_0 < \omega_1 < \dots < \omega_N = \pi N / 2L \tag{1.2}$$

and such that the even ω_j are eigenvalues for I, the odd for II, then there exists a unique rod with piecewise constant A(x), such that

$$A(x) = A_j \qquad (j-1)\Delta < x \leqslant j\Delta \tag{1.3}$$

where $\Delta = L/N$, j = 1, 2, ..., N, $A_1 = 1$. He presented an algorithm for the determination of the A_j .

The purpose of this paper is to place Andersson's algorithm within the context of inversion algorithms in seismology and transmission line theory [2,3]. In that context, a medium with parameters that are piecewise constant over equal intervals of depth Δ , such as (1.3), is called a Goupillaud medium. In seismology and transmission line theory, as in most inverse scattering problems, the data does not relate to eigenvalues; there are no eigenvalues, or so-called bound states. Instead the data refers to the response to an input. One way of expressing the data uses the reflected wave U(t) at equal intervals 2Δ , due to an incoming wave D(t) also sampled at intervals 2Δ . One of the fundamental questions is to ask whether a given reflected wave and incoming wave actually correspond to a Goupillaud medium. This is the question: 'Is the data realizable?' The realizability criterion can be phrased by introducing the Z-transforms, U(z) and D(z), of U(t) and D(t), and defining the left-reflection function

$$R(z) = \frac{U(z)}{D(z)} \tag{1.4}$$

and then putting

$$f_1(z) = z^{-1}R(z). (1.5)$$

The criterion is

$$M(f_1) \equiv \sup_{|z| \le 1} |f_1(z)| \le 1.$$
 (1.6)

Schur [4] constructed an algorithm to test whether a function $f_1(z)$ satisfies (1.6), that is, is bounded by 1 on the unit disc. It is based on the fact that if $|\gamma| < 1$, then

$$w = \frac{z - \gamma}{1 - \bar{\gamma}z} \tag{1.7}$$

maps $|z| \le 1$ onto $|w| \le 1$ and |z| = 1 onto |w| = 1. Schur's algorithm is based on the recurrence

$$f_j(z) = \frac{1}{z} \frac{f_{j-1}(z) - \gamma_j}{1 - \bar{\gamma}_j f_{j-1}(z)} \qquad j = 2, 3, \dots$$
 (1.8)

where $\gamma_j = f_{j-1}(0)$. Suppose $M(f_{j-1}) \leqslant 1$. There are two possibilities: either $|\gamma_j| = 1$, in which case the condition $M(f_{j-1}) \leqslant 1$ and the maximum modulus principle (Knopp [5], p 84) forces $f_{j-1}(z) = \gamma_j$, so that the sequence terminates at $f_{j-1}(z)$; or $|\gamma_j| < 1$, in which case $M(f_j) \leqslant 1$. Thus the condition (1.6) used with the recurrence (1.8) leads to a finite or infinite sequence, $\gamma_2, \gamma_3, \ldots$, with the property $|\gamma_j| \leqslant 1$, where the inequality is strict except possibly for the last one. We note in particular that if $M(f_1) = 1$, then $M(f_j) = 1$ for all j, and if the sequence terminates at j = N + 1, it will do so with $|f_N| = 1$.

2. Formulation

First we replace equation (1.1) by two coupled first-order equations, namely

$$w'(x) = i\omega p(x)/A(x) \tag{2.1}$$

$$p'(x) = i\omega A(x)w(x). \tag{2.2}$$

Put

$$\eta(x) = \{A(x)\}^{1/2} \tag{2.3}$$

and define down and up quantities

$$D = \frac{1}{2} \{ \eta w + \eta^{-1} p \} \tag{2.4}$$

$$U = \frac{1}{2} \{ \eta w - \eta^{-1} p \}. \tag{2.5}$$

These satisfy the equations

$$D' = i\omega D + \eta' \eta^{-1} U \tag{2.6}$$

$$U' = -i\omega U + \eta' \eta^{-1} D \tag{2.7}$$

so that if A(x) = constant, then $\eta' = 0$ and

$$D' = i\omega D \qquad U' = -i\omega U \tag{2.8}$$

which have the solutions

$$D = D_0 e^{i\omega x} \qquad U = U_0 e^{-i\omega x}. \tag{2.9}$$

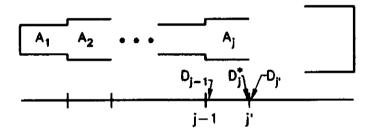


Figure 1. Beam of piecewise constant cross-section.

Suppose A(x) has the form (1.3). Define the quantities

$$D_{j} = D(j\Delta +) \qquad U_{j} = U(j\Delta +) \qquad D_{j}^{*} = D(j\Delta -) \qquad U_{j}^{*} = U(j\Delta -). \tag{2.10}$$

Then equations (2.9) and figure 1 show that

$$D_i^* = e^{i\omega\Delta} D_{i-1} \qquad U_i^* = e^{-i\omega\Delta} U_{j-1}.$$
 (2.11)

Put $e^{i\omega \Delta} = z^{1/2}$, then

$$\begin{bmatrix} D_{j}^{*} \\ U_{i}^{*} \end{bmatrix} = \begin{bmatrix} z^{1/2} & 0 \\ 0 & z^{-1/2} \end{bmatrix} \begin{bmatrix} D_{j-1} \\ U_{j-1} \end{bmatrix}. \tag{2.12}$$

Let

$$\mathbf{H}_{j} = \frac{1}{2} \begin{bmatrix} \eta_{j} & \eta_{j}^{-1} \\ \eta_{i} & -\eta_{i}^{-1} \end{bmatrix}. \tag{2.13}$$

Then equations (2.4), (2.5) and the continuity of w and p across a discontinuity of A(x) give

$$\begin{bmatrix} D_{j-1} \\ U_{j-1} \end{bmatrix} = \mathbf{H}_j \begin{bmatrix} w_{j-1} \\ p_{j-1} \end{bmatrix} \qquad \begin{bmatrix} D_{j-1}^* \\ U_{j-1}^* \end{bmatrix} = \mathbf{H}_{j-1} \begin{bmatrix} w_{j-1} \\ p_{j-1} \end{bmatrix}$$
(2.14)

so that

$$\begin{bmatrix} D_{j-1} \\ U_{j-1} \end{bmatrix} = \mathbf{H}_j \mathbf{H}_{j-1}^{-1} \begin{bmatrix} D_{j-1}^* \\ U_{j-1}^* \end{bmatrix}. \tag{2.15}$$

The matrix

$$\Theta_j = \mathbf{H}_j \mathbf{H}_{j-1}^{-1} \tag{2.16}$$

may be written

$$\Theta_{j} = \frac{1}{\sigma_{j}} \begin{bmatrix} 1 & -\gamma_{j} \\ -\gamma_{j} & 1 \end{bmatrix}$$
 (2.17)

where

$$\sigma_j = (1 - \gamma_j^2)^{1/2}$$
 $\gamma_j = \frac{A_{j-1} - A_j}{A_{j-1} + A_j}$ (2.18)

We can combine equations (2.11) and (2.14) to obtain

$$\begin{bmatrix} D_j^* \\ U_j^* \end{bmatrix} = \begin{bmatrix} z^{1/2} & 0 \\ 0 & z^{-1/2} \end{bmatrix} \Theta_j \begin{bmatrix} D_{j-1}^* \\ U_{j-1}^* \end{bmatrix}. \tag{2.19}$$

Put

$$\frac{U_j^*}{D_j^*} = f_j(z), (2.20)$$

then equation (2.18) gives

$$f_{j}(z) = \frac{1}{z} \cdot \frac{f_{j-1}(z) - \gamma_{j}}{1 - \gamma_{j} f_{j-1}(z)}$$
(2.21)

which, since γ_j is real, is precisely Schur's recurrence (1.8).

3. The forward problem

Suppose that we are given the parameters $(A_j)_1^N$ and we wish to find the eigenvalues corresponding to the end conditions I and II. Suppose that the rod is vibrating with frequency ω and that the end condition at x = L is satisfied, then without loss of generality we can take (see (2.1))

$$w(L) = 1$$
 $w'(L) = 0 = p(L).$ (3.1)

Then $D_N^* = \eta_N/2 = U_N^*$ so that

$$f_N(z) = 1. (3.2)$$

The values of $w(0) = w_0$, $p(0) = p_0$ are given by

$$D_0 = \frac{1}{2} \{ \eta_0 w_0 + \eta_0^{-1} p_0 \} \tag{3.3}$$

$$U_0 = \frac{1}{2} \{ \eta_0 w_0 - \eta_0^{-1} p_0 \} \tag{3.4}$$

so that

$$\eta_0^2 \frac{w_0}{p_0} = \frac{D_0 + U_0}{D_0 - U_0} = \frac{z^{-1/2} D_1^* + z^{1/2} U_1^*}{z^{-1/2} D_1^* - z^{1/2} U_1^*} \\
= \frac{1 + g(z)}{1 - g(z)}$$
(3.5)

where

$$g(z) = zf_1(z). (3.6)$$

In the forward problem, we are given $f_N(z) = 1$ and we are given the $(\gamma_j)_2^N$ with $|\gamma_j| < 1$. We may thus compute $f_{N-1}, f_{N-2}, \dots, f_1$, using the recurrence (2.20) in the reverse form, namely

$$f_{j-1}(z) = \frac{zf_j(z) + \gamma_j}{1 + \gamma_j zf_j(z)} \qquad j = N, N - 1, \dots, 2.$$
(3.7)

The mapping of $zf_j(z)$ onto $f_{j-1}(z)$ has the form (1.6). Thus the region $|zf_j(z)| \leq 1$ is mapped onto $|f_{j-1}(z)| \leq 1$, and $|zf_j(z)| = 1$ is mapped onto $|f_{j-1}(z)| = 1$. But $f_N(z) = 1$ so that each $(f_j(z))_1^N$ has $|f_j(z)| = 1$ when |z| = 1, i.e. when ω is real. Thus the function w = g(z) maps $|z| \leq 1$ onto $|w| \leq 1$, and |z| = 1 onto |w| = 1. When g(z) is expressed in terms of z it has the form

$$g(z) = \frac{z P_{N-1}(z)}{Q_{N-1}(z)} \tag{3.8}$$

where P_{N-1} and Q_{N-1} are polynomials of degree N-1. Thus g(z) maps the circle |z|=1 into itself N times.

Equation (3.7) shows that if $f_j(z^{-1}) = 1/f_j(z)$, then $f_{j-1}(z^{-1}) = 1/f_{j-1}(z)$. But $f_N(z^{-1}) = 1 = 1/f_N(z)$, so that indeed

$$f_j(z^{-1}) = 1/f_j(z)$$
 $j = 1, 2, ..., N$ (3.9)

and hence

$$g(z^{-1}) = 1/g(z). (3.10)$$

The mapping of |z| = 1 into itself caused by g(z) produces two sets of N points on |z| = 1 of significance, namely

$$A = \{z \mid |z| = 1 \text{ and } g(z) = 1\}$$

 $B = \{z \mid |z| = 1 \text{ and } g(z) = -1\}.$

The points in \mathcal{A} correspond to values of z for which, according to (3.5), $p_0 = 0$; the z values give values of ω which are eigenvalues of I. Similarly the z values in \mathcal{B} give $w_0 = 0$ so that ω corresponds to an eigenvalue of II. The known interlacing of these two sets of eigenvalues means that the points of \mathcal{A} and \mathcal{B} will interlace on the circle |z| = 1. Equation (3.10) shows that if z is a member of either set, then $z^{-1} = \overline{z}$ is a member of the same set. Figure 2 shows the arrangement of the two sets when N = 2 and N = 3. Since g(1) = 1 and $g(-1) = (-1)^N$, therefore z = 1 is in \mathcal{A} , while z = -1 is in \mathcal{A} if N is even, and in \mathcal{B} if N is odd. It may easily be verified that there are N + 1 values of z in $\mathcal{A} \setminus \mathcal{B}$ which satisfy

$$0 \leqslant \arg(z) \leqslant \pi \tag{3.11}$$

and the remaining N-1 values may be obtained as $z^{-1} = \bar{z}$, where z satisfies (3.10). The N+1 values of z satisfying (3.11) yield N+1 eigenvalues ω_j satisfying (1.2). Since $z=\mathrm{e}^{2\mathrm{i}\omega\Delta}$ is a periodic function of ω with period $\pi/\Delta=N\pi/L$, each value of z gives rise to an infinite sequence of eigenvalues with equal spacing $N\pi/L$, and each $z^{-1}=\mathrm{e}^{-2\mathrm{i}\omega\Delta}$ gives another such sequence. Thus the system not only has the eigenvalues $\omega_0,\omega_1,\ldots,\omega_N$, but also

$$\omega_{2N+k} = N\pi/L + \omega_k$$
 $\omega_{2N-k} = N\pi/L - \omega_k$ $k = 0, \pm 1, \pm 2, \dots$ (3.12)

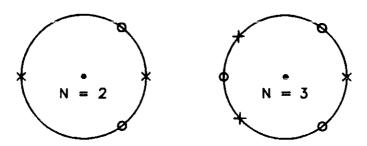


Figure 2. The members of A(x) and B(0) interlace on the circle.

4. The inverse problem

Now we are given N+1 eigenvalues ω_j satisfying (1.2). We must use them to construct g(z) and hence $f_1(z)$, and then find the γ_j which will lead eventually to $f_N(z) = 1$.

It is convenient to make a distinction between even and odd values of N. In the case when N is even, let N=2M. Of the $N+1\equiv 2M+1$ eigenvalues, M+1 are even, corresponding to I; the set \mathcal{A} consists of 2M points: $z_0=1,\ z_N=-1$, and the M-1 pairs $z_{2j},z_{2j}^{-1},\ j=1,2,\ldots,M-1$. The 2M odd z's in \mathcal{B} occur in M pairs $z_{2j-1},z_{2j-1}^{-1},\ j=1,2,\ldots,M$. Thus

$$\frac{\eta_0^2 w_0}{p_0} = \frac{1 + g(z)}{1 - g(z)} = \frac{C \prod_{j=1}^{M} (z - z_{2j-1})(z - z_{2j-1}^{-1})}{(z^2 - 1) \prod_{j=1}^{M-1} (z - z_{2j})(z - z_{2j}^{-1})}$$
(4.1)

so that g(z) = 1 when z is a root of the denominator, and g(z) = -1 when z is a root of the numerator. The constant, C must be chosen so that g(0) = 0, i.e. C = -1; the numerator of g(z) will then have no constant term in its power series expansion, while the highest powers in the denominator, z^{2M} , will cancel, so that g(z) will have the form (3.8). Denote the right-hand side of equation (4.1) by f(z), so that

$$\frac{1+g(z)}{1-g(z)} = f(z) = \zeta. \tag{4.2}$$

The function f(z) will map the open, connected region

$$\mathcal{R} = \{ z \mid |z| < 1 \}$$

into an open, connected region in the ζ -plane. The function f(z) maps the origin z=0 onto $\zeta=1$, and |z|=1 into the imaginary axis. We conclude that f(z) maps $|z| \leq 1$ into the right-hand half-plane, so that

if
$$|z| \le 1$$
 then Re $f(z) \ge 0$
if $|z| = 1$ then Re $f(z) = 0$.

Since the given eigenvalues, ω_j , corresponding to I and II interlace, i.e. the members of \mathcal{A} and \mathcal{B} interlace, then as we proceed counterclockwise around |z|=1 starting from z=1, the points of \mathcal{A} and \mathcal{B} are mapped successively onto the point at infinity and the origin in the ζ -plane. Equation (4.2) implies

$$g(z) = \frac{f(z) - 1}{f(z) + 1} = \frac{\zeta - 1}{\zeta + 1}.$$
 (4.3)

But if Re $\zeta \equiv \xi \geqslant 0$, then ζ is no further from 1 than it is from -1, that is $|\zeta - 1| \leqslant |\zeta + 1|$ so that $|g(z)| \leqslant 1$. We conclude that g(z), and hence, by the Schwarz lemma, $f_1(z)$, is bounded by 1 on the unit disc.

Now apply Schur's algorithm to $f_1(z)$ to produce a sequence $\{f_j(z)\}_1^N$. The form of g(z) given by (3.8) leads to a form

$$f_1(z) = P_{N-1}(z)/Q_{N-1}(z) \tag{4.4}$$

with real coefficients. Therefore all γ_j will be real. Equation (4.1) shows that g(z) has the properties

$$g(z^{-1}) = 1/g(z)$$
 $g(1) = 1.$ (4.5)

Therefore $f_1(z^{-1}) = 1/f_1(z)$, and $f_1(1) = 1$. Equation (1.8) now shows that

$$f_j(z^{-1}) = 1/f_j(z)$$
 $f_j(1) = 1$ $j = 1, 2, ..., N$ (4.6)

because the statement is true for j = 1. Thus $f_j(z)$ will have the form

$$f_j(z) = P_{N-j}(z)/Q_{N-j}(z)$$
 $j = 1, 2, ..., N$ (4.7)

so that the sequence will converge with $f_N(z) = 1$ as required, and the γ_j will satisfy

$$-1 < \gamma_j < 1$$
 $j = 2, 3, ..., N; \quad \gamma_{N+1} = 1.$ (4.8)

Since $A_1 = 1$, by assumption, these γ_j lead to a unique set of finite, positive $(A_j)_1^N$ as required. We stress that the single condition (1.6) ensures the existence of the γ_i satisfying (4.8).

In the case when N is odd, let N = 2M - 1. Of the $N + 1 \equiv 2M$ eigenvalues, M are even and M are odd; the set \mathcal{A} consists of $z_0 = 1$ and M-1 pairs z_{2j} , z_{2j}^{-1} , j = $1,2,\ldots,M-1$. The 2M-1 odd z's in $\mathcal B$ are $z_N=-1$ and M-1 pairs $z_{2j-1},\ z_{2j-1}^{-1},\ j=1,2,\ldots,M-1$ $1, 2, \dots, M - 1$. Now

$$\frac{\eta_0^2 w_0}{p_0} = \frac{1 + g(z)}{1 - g(z)} = \frac{C(z+1) \prod_{j=1}^{M-1} (z - z_{2j-1})(z - z_{2j-1}^{-1})}{(z-1) \prod_{j=1}^{M-1} (z - z_{2j})(z - z_{2j}^{-1})}$$
(4.9)

where again g(0) = 0 implies C = -1. Apart from this, the argument follows as

For computational purposes, Schur's algorithm leads to a recurrence relation for the coefficients in the polynomials $P_{N-j}(z)$ and $Q_{N-j}(z)$. Let

$$P_{N-j}(z) = \sum_{k=0}^{N-j} a_{N-j,k} z^k \qquad Q_{N-j}(z) = \sum_{k=0}^{N-j} b_{N-j,k} z^k.$$
 (4.10)

Equation (4.10) or (4.9) yields the values of $a_{N-1,k}$ and $b_{N-1,k}$ from data. Equation (4.6) states that

$$a_{N-j,k} = b_{N-j,N-j-k}$$
 $k = 0, 1, 2, \dots, N-j.$ (4.11)

The recurrence (2.20) yields

$$\gamma_j = a_{N-j+1,0}/b_{N-j+1,0} \tag{4.12}$$

$$a_{N-j,k} = a_{N-j+1,k+1} - \gamma_j b_{N-j+1,k+1}$$
 $k = 0,1,2,\ldots,N-j$ (4.13)

$$b_{N-j,k} = b_{N-j+1,k} - \gamma_j a_{N-j+1,k} \qquad k = 0, 1, 2, \dots, N-j.$$
 (4.14)

Just as the sequences $\{a_{N-j+1,k}\}_{k=0}^{N-j+1}$ and $\{b_{N-j+1,k}\}_{k=0}^{N-j+1}$ consist of the same numbers, in opposite orders, so equations (4.13) and (4.14) will produce sequences $\{a_{N-j,k}\}_{k=0}^{N-j}$ and $\{b_{N-j,k}\}_{k=0}^{N-j}$ consisting of the same numbers in opposite orders. In its simplest terms the algorithm has three steps; we have adapted the procedure

of Kailath and Lev-Ari [6]:

Take the coefficients of $P_{N-1}(z)$ from equation (4.1) or (4.9) and construct the $2 \times N$ matrix

$$\mathbf{G}_0 = \begin{bmatrix} a_0 & a_1 & \cdots & a_{N-1} \\ a_{N-1} & a_{N-2} & \cdots & a_0 \end{bmatrix}.$$

II. Compute $\gamma_2 = a_0/a_{N-1}$ and construct

$$\mathbf{G}_1' = \begin{bmatrix} 1 & -\gamma_2 \\ -\gamma_2 & 1 \end{bmatrix} \mathbf{G}_0 = \begin{bmatrix} 0 & a_0' & a_1' & \cdots & a_{N-3}' & a_{N-2}' \\ a_{N-2}' & a_{N-3}' & & \cdots & a_0' & 0 \end{bmatrix}.$$

III. Shift the top row of the matrix formed in II to the left and delete the last column to form the $2 \times (N-1)$ matrix

$$\mathbf{G}_{1} = \begin{bmatrix} a'_{0} & a'_{1} & \cdots & a'_{N-2} \\ a'_{N-2} & a'_{N-1} & \cdots & a'_{0} \end{bmatrix}$$

and go to step I.

5. Conclusions

We have shown that Schur's algorithm ensures the existence of, and provides an algorithm for computing, the set of N values of the Goupillaud model of the Sturm-Liouville equation in impedance form. Schur's algorithm is known to be computationally stable and efficient [3].

We note that by making trivial changes in the analysis we can construct the Goupillaud model from N interlacing eigenvalues, $0 < \omega_1 < \omega_2 < \cdots < \omega_N = \pi N/2L$, corresponding to

I.
$$w'(0) = 0 = w(L)$$
 odd ω_j
II. $w(0) = 0 = w(L)$ even ω_j .

However, it is not possible to use the essentially algebraic method of this paper to construct the A_i from the eigenvalues $0<\omega_1<\omega_2<\cdots<\omega_N$ corresponding to the general end conditions

I.
$$w'((0) = 0 = w'(L) + Hw(L)$$

II. $w(0) = 0 = w'(L) + Hw(L)$.

This is because ω will appear in the analysis as itself, and not just in the form $e^{2i\omega\Delta}$. It is possible also to apply the analysis to the equation

$$w''(x) + \lambda \rho(x)w(x) = 0 \tag{5.1}$$

which appears in connection with string vibrations, since this may be transformed into (1.1) with an appropriate change of variable.

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